

1. (5 points) Describe the K-means algorithm (1pt). Prove that K-means converges to a local minimum (2pts). Describe the K-means++ algorithm (1pt). Give an example when employing K-means++ leads, on average, to better solution than K-means (1pt).

2. (5 points) Formulate the logistic regression problem (1 point). Derive the gradient descent learning method for this task (2.5 points).

Given the training set $T = \{(-1, -1), (-2, -1), (0, 1), (2, 1)\}$, starting point $w = (0, 0)$, and an initial step size of 1, do the first iteration of gradient descent. (1.5 points).

$$\alpha(x) = \ln \frac{P(1|x)}{P(2|x)} = \vec{w} \cdot \vec{x} \rightarrow \begin{pmatrix} x_0 \\ x_1 \end{pmatrix}^T \begin{pmatrix} w_0 & w_1 & \dots & w_k \end{pmatrix} \rightarrow P(1|x) = \frac{1}{1 + e^{-\vec{w} \cdot \vec{x}}} \\ P(2|x) = \frac{1}{1 + e^{+\vec{w} \cdot \vec{x}}}$$

gradient descent
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$$E(w) = -l'(w) = -\sum \ln(P(k|x)) = -\sum \ln(1 + e^{-\vec{w} \cdot \vec{x}})$$

$$g(w) = \frac{\partial E(w)}{\partial w} = -\sum \frac{1}{(1 + e^{-\vec{w} \cdot \vec{x}})} \cdot \vec{w} \cdot \vec{x} = -\sum (1 - P(k|x)) \cdot \vec{w} \cdot \vec{x}$$

gradient descent iteration

$$w = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad x_i = (1, x), \quad \underbrace{\vec{w} \cdot \vec{x} = \pm 1}_{\text{step } 1}, \quad E(w) = \sum \ln(1 + e^{-\vec{w} \cdot \vec{x}}) \\ g(w) = \sum (1 - P(k|x)) \cdot \vec{w} \cdot \vec{x} = \sum \frac{1}{1 + e^{-\vec{w} \cdot \vec{x}}} \cdot \vec{w} \cdot \vec{x}$$

$$E(w) = \ln(1 + e^{0+0}) + \ln(1 + e^{0+1}) + \dots = \ln(2) + \ln(2) + \dots \\ e^0 = e^0 = 1, \quad \dots e^0 = \dots = \ln(2) / 4 \\ \begin{pmatrix} 0, 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 0+0=0$$

$$g(w_0) = \frac{(-1) \cdot [1, -1]}{1 + \sum_{k=1}^2 (1, k) \cdot [1, -1]} + \dots = \frac{1}{2} \cdot ((-1, 1) + (-1, 2) + (-1, 0) + (-1, -2)) = \frac{1}{2} \cdot (-4, 1) = (-2, 1/2)$$

$$\underbrace{e^0 = 1}_{(-1, 1)} \quad \frac{1}{2}$$

iterate $t=1$

$$w_1 = w - \text{step} \cdot g = (0, 0) - 1 \cdot (-2, 1/2) = (2, -1/2)$$

$$E_1(w) = \sum \ln(1 + e^{-\vec{w} \cdot \vec{x}}) \quad 2+1=3 \\ x_i = (1, -1, -1) \\ = \ln(1 + e^{-\vec{w} \cdot \vec{x}}) \\ \ln(1 + e^{-3})$$

3. (5 points) Parameter Estimation. The reliability of light bulbs is defined by the probability density function

$$p(t) = \frac{1}{\theta (\frac{t}{\theta} + 1)^2}, \quad t \in [0, \infty],$$

where $p(t)\delta$ is the probability that a bulb fails in a short time interval $(t, t + \delta)$. That is, the probability $P(T)$ that the bulb fails in interval $(0, T)$, is

- a) parameter θ if in an experiment with two bulbs the following lifetimes have been observed:
 $t_1 = 1.0, t_2 = 4.0$ (4pts)

- b) For this setting, what is the probability that a light bulb is still OK at time 10? (1pt)

$$\text{ML: } \hat{\theta} = \arg\max L(\theta) = \arg\max \prod_{i=1}^n p(x_i, \theta) \\ L(\theta) = \frac{1}{\theta (\frac{t_1}{\theta} + 1)^2} \cdot \frac{1}{\theta (\frac{t_2}{\theta} + 1)^2} \\ L(\theta) = \ln(L(\theta)) = \ln \frac{1}{\theta (\frac{t_1}{\theta} + 1)^2} + \ln \frac{1}{\theta (\frac{t_2}{\theta} + 1)^2} \\ L(\theta) = \ln(1) - \ln(\theta \cdot (\frac{t_1}{\theta} + 1)^2) + \ln(1) - \ln(\dots) \\ L(\theta) = -\ln(\theta) - \ln(\frac{t_1}{\theta} + 1)^2 - \ln(\theta) - \ln(\frac{t_2}{\theta} + 1)^2 \\ L(\theta) = -2\ln(\theta) - \frac{t_1^2}{\theta^2} - 2\ln(t_1 + \theta) + 2\ln(\theta)$$

$$\text{b) } P(b) = 1 - P(10) = 1 - \frac{1}{\frac{T}{\theta} + 1} = 1 - \frac{1}{\frac{10}{\theta} + 1} = 1 - \frac{1}{\frac{10}{4} + 1} = 1 - \frac{1}{5 + 1} = 1 - \frac{1}{6} = \underline{\underline{0.1}}$$

$$g(\mathbf{w}) = \frac{\partial E(\mathbf{w})}{\partial \mathbf{w}} = \sum_{(\mathbf{x}, k) \in T} \frac{e^{-k\mathbf{w} \cdot \mathbf{x}}}{1 + e^{-k\mathbf{w} \cdot \mathbf{x}}} (-k\mathbf{x}) = - \sum_{(\mathbf{x}, k) \in T} \frac{1}{1 + e^{k\mathbf{w} \cdot \mathbf{x}}} k\mathbf{x} \\ = - \sum_{(\mathbf{x}, k) \in T} (1 - p(k|\mathbf{x})) k\mathbf{x}.$$

$$E(\mathbf{w}) = - \sum_{(\mathbf{x}, k) \in T} \ln p(k|\mathbf{x}) = \sum_{(\mathbf{x}, k) \in T} \ln(1 + e^{-k\mathbf{w} \cdot \mathbf{x}})$$

$$\begin{aligned}
 l(\theta) &= -\ln(\theta) - \ln\left(\frac{t_1}{\theta} + 1\right)^2 - \ln(\theta) - \ln\left(\frac{t_2}{\theta} + 1\right)^2 \\
 l(\theta) &= -2\ln(\theta) - \underbrace{\frac{2}{t_1+\theta}}_{\theta} - 2\ln(t_1+\theta) + 2\ln(\theta) \\
 &\quad - 2\ln\left(\frac{t_2+\theta}{\theta}\right) \\
 l(\theta) &= 2\ln(\theta) - 2\ln(t_1+\theta) - 2\ln(t_2+\theta) \\
 \frac{\partial l(\theta)}{\partial \theta} &= \frac{2}{\theta} - \frac{2}{t_1+\theta} - \frac{2}{t_2+\theta} = 0 \\
 t_1 = 1.0 \quad \} & \quad \frac{2}{\theta} - \frac{2}{1+\theta} - \frac{2}{4+\theta} = 0 \\
 t_2 = 4.0 & \\
 2 \cdot [1+\theta] \cdot (4+\theta) - 2\theta \cdot (4+\theta) - 2\theta \cdot (1+\theta) &= 0 \\
 \theta \cdot (1+\theta) \cdot (4+\theta) & \\
 (2+2\theta) \cdot (4+\theta) - 8\theta - 2\theta^2 - 2\theta - 2\theta^2 &= 0 \\
 8 + 2\theta + 8\theta + 2\theta^2 - 8\theta - 2\theta^2 - 2\theta - 2\theta^2 &= 0 \\
 -2\theta^2 + 8 &= 0 \\
 \theta^2 = \frac{-8}{-2} &= 4 \\
 \theta = \pm\sqrt{4} = \pm 2 &
 \end{aligned}$$

4. (5 points) Decision tree classifiers.

- (a) (2 points) Describe the simplest top-down tree-building algorithm that selects the decision rule at a node by maximization of information gain.
- (b) (3 points) Discuss advantages and disadvantages of decision trees.